



Inputs for **coordinate system**:

- “**Global**” (default)
- “**ID** (“1”, “2”, etc.) for local coordinate systems

Quick RBE Springs

RBE Bodies: Spring1

Spring stiffness:

Coord. System ID	Global
Dx	1e08 N/mm
Dy	1e08 N/mm
Dz	0 N/mm
Rx	0 N*mm/rad
Ry	0 N*mm/rad
Rz	500 N*mm/rad
Parametric	<input checked="" type="checkbox"/>

Apply OK Cancel

**RBE bodies to convert**

- RBE names are used for connectors;
- If RBE are merged, springs will be grouped accordingly

**Spring Stiffnesses**  
*Parametric* option will use SimLab parameters

Translational Stiffness:

☒ X, X \$DxStiff

☒ Y, Y \$DyStiff

☐ Z, Z \$DzStiff

Rotational Stiffness:

☐ X, X \$RxStiff

☐ Y, Y \$RyStiff

☒ Z, Z \$RzStiff